

# Package: GLmom (via r-universe)

May 14, 2026

**Type** Package

**Title** Generalized L-Moments Estimation for Extreme Value Distributions

**Version** 1.3.1

**Description** Provides generalized L-moments estimation methods for the generalized extreme value ('GEV') distribution. Implements both stationary 'GEV' and non-stationary 'GEV11' models where location and scale parameters vary with time. Includes various penalty functions ('Martins'-'Stedinger', Park, Cannon, 'Coles'-Dixon) for shape parameter regularization. Also provides model averaging estimation ('ma.gev') that combines MLE and L-moment methods with multiple weighting schemes for robust high quantile estimation. The 'GLME' methodology is described in Shin et al. (2025a) [doi:10.48550/arXiv.2512.20385](https://doi.org/10.48550/arXiv.2512.20385). The non-stationary L-moment method is based on Shin et al. (2025b) [doi:10.1007/s42952-025-00325-3](https://doi.org/10.1007/s42952-025-00325-3). The model averaging method is described in Shin et al. (2026) [doi:10.1007/s00477-025-03167-x](https://doi.org/10.1007/s00477-025-03167-x). See also 'Hosking' (1990) [doi:10.1111/j.2517-6161.1990.tb01775.x](https://doi.org/10.1111/j.2517-6161.1990.tb01775.x) for L-moments theory and 'Martins' and 'Stedinger' (2000) [doi:10.1029/1999WR900330](https://doi.org/10.1029/1999WR900330) for penalized likelihood methods.

**License** GPL (>= 3)

**URL** <https://github.com/sygstat/GLmom>

**BugReports** <https://github.com/sygstat/GLmom/issues>

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bangkok

*Bangkok Maximum Rainfall Data*

---

### Description

Annual maximum daily rainfall data from Bangkok, Thailand. This dataset is used for demonstrating model averaging methods for high quantile estimation in extreme value analysis.

### Usage

bangkok

**Format**

A data frame with 58 rows and 5 columns:

**X1** Annual maximum daily rainfall in mm (numeric)

**X2** 2nd largest annual daily rainfall in mm (numeric)

**X3** 3rd largest annual daily rainfall in mm (numeric)

**X4** 4th largest annual daily rainfall in mm (numeric)

**X5** 5th largest annual daily rainfall in mm (numeric)

**Source**

Thai Meteorological Department (TMD; <https://www.tmd.go.th>)

**References**

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

**Examples**

```
data(bangkok)
head(bangkok)

# Estimate high quantiles using model averaging
result <- ma.gev(bangkok$X1, quant = c(0.99, 0.995))
print(result$qua.ma)
```

---

gado.prop\_11

*Comprehensive Non-stationary GEV Estimation*

---

**Description**

Estimates parameters of a non-stationary GEV distribution using multiple methods: Weighted Least Squares (WLS), GN16 method, and the proposed L-moment method from Shin et al. (2025, J. Korean Stat. Soc.).

This is a convenience wrapper around [glme.gev11](#) with `pen="no"`, providing compatibility with the original `nsgev` package interface.

**Usage**

```
gado.prop_11(xdat, ntry = 20, ftol = 1e-06)
```

**Arguments**

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts for optimization (default 20).
ftol	Function tolerance for optimization (default 1e-6).

**Value**

A list containing:

- para.prop - L-moment based estimates (proposed method).
- para.gado - GN16 method estimates.
- para.wls - Weighted least squares estimates.
- strup.org - Original non-stationary WLSE by Strup method.
- lme.sta - Stationary L-moment estimates.

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 54, 947-970. doi:10.1007/s42952025003253

**See Also**

[glme.gev11](#) for the full GLME method with penalty functions, [nsgev](#) for the simple interface.

**Examples**

```
data(Trehafod)
result <- gado.prop_11(Trehafod$r1, ntry = 5)
print(result$para.prop)
print(result$lme.sta)
```

---

glme.gev

*Generalized L-moments estimation for generalized extreme value distribution*

---

**Description**

This function estimates the Generalized L-moments of Generalized Extreme Value distribution.

**Usage**

```
glme.gev(
  xdat,
  ntry = 10,
  pen = "beta",
  pen.choice = NULL,
  mu = -0.5,
  std = 0.2,
  p = 6,
  c1 = 10,
  c2 = 5
)
```

**Arguments**

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts for parameter estimation. Higher values increase the chance of finding a more accurate estimate by trying different initial conditions.
pen	Type of penalty function: Choose among "norm", "beta" (default), "ms", "park", "cannon", "cd", and "no" (without penalty function).
pen.choice	Choice number of penalty function specifying hyperparameters. For "beta": 1-6 correspond to different (p, c1, c2) combinations. For "norm": 1-4 correspond to different (mu, std) combinations.
mu	Mean hyperparameter for "norm" penalty function (default -0.5).
std	Standard deviation hyperparameter for "norm" penalty function (default 0.2).
p	Shape hyperparameter for "beta" penalty function (default 6).
c1	Scaling hyperparameter for "beta" penalty function (default 10).
c2	Upper limit hyperparameter for "beta" penalty function (default 5).

**Details**

The equations for the L-moments for LME of the GEVD are

$$\underline{\lambda} - \underline{\mathbf{1}} = \underline{\mathbf{0}},$$

where  $\underline{\lambda} = (\lambda_1, \lambda_2, \lambda_3)^t$  and  $\underline{\mathbf{1}} = (l_1, l_2, l_3)^t$ . Next, we define the generalized L-moments distance (GLD) as;

$$(\underline{\lambda} - \underline{\mathbf{1}})^t V^{-1} (\underline{\lambda} - \underline{\mathbf{1}}),$$

where  $V$  is the variance-covariance matrix of the sample L-moments up to the third order.

**Value**

The glme.gev function returns a list containing the following elements:

- para.glme - The estimated parameters of the Generalized Extreme Value distribution.
- para.lme - The L-moment estimates of the parameters.

- covinv.lmom - The inverse of the covariance matrix of the L-moments.
- lcovdet - The log determinant of the covariance matrix.
- nllh.glme - The negative log-likelihood of the GLME solution.
- pen - The penalization method used.
- p\_q - (for beta penalty) The p and q values used.
- c1\_c2 - (for beta penalty) The c1 and c2 values used.
- mu\_std - (for norm penalty) The mu and std values used.

### Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

### References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

### See Also

[glme.gev11](#) for non-stationary GEV estimation, [ma.gev](#) for model averaging estimation, [glme.like](#) for the objective function, [quagev.NS](#) for quantile computation.

### Examples

```
# Load example streamflow data
data(streamflow)
x <- streamflow$r1

# Estimate GEV parameters using beta penalty (default)
result <- glme.gev(x, ntry = 5)
print(result$para.glme)

# Using Martins-Stedinger penalty
result_ms <- glme.gev(x, ntry = 5, pen = "ms")
print(result_ms$para.glme)
```

---

glme.gev11

*Generalized L-moments estimation for non-stationary GEV11 model*

---

### Description

This function estimates parameters of the non-stationary GEV11 model where  $\mu(t) = \mu_0 + \mu_1 * t$  and  $\sigma(t) = \exp(\sigma_0 + \sigma_1 * t)$ .

**Usage**

```
glme.gev11(
  xdat,
  ntry = 10,
  ftol = 1e-06,
  init.rob = TRUE,
  glme.pre = "wls",
  opt.choose = "gof",
  pen = "beta",
  pen.choice = NULL,
  mu = -0.55,
  std = 0.3,
  p = 6,
  c1 = 10,
  c2 = 5
)
```

**Arguments**

xdat	A numeric vector of data to be fitted.
ntry	Number of attempts for parameter estimation (default 10).
ftol	Tolerance for convergence (default 1e-6).
init.rob	Use robust regression for initialization (default TRUE).
glme.pre	Pre-estimation method: "wls" (default) or "gado".
opt.choose	Selection criterion: "gof" (default, goodness-of-fit) or "nllh" (negative log-likelihood).
pen	Type of penalty function: "norm", "beta" (default), "ms", "park", "cannon", "cd", or "no".
pen.choice	Choice number for penalty hyperparameters (default 6 for beta).
mu	Mean for normal penalty (default -0.55).
std	Std for normal penalty (default 0.3).
p	Shape for beta penalty (default 6).
c1	Scaling for beta penalty (default 10).
c2	Limit for beta penalty (default 5).

**Value**

A list containing:

- para.glme - Proposed GLME estimates (5 parameters: mu0, mu1, sigma0, sigma1, xi).
- para.lme - L-moment based estimates for non-stationary model.
- para.gado - GN16 original estimates.
- para.wls - Weighted least squares estimates (WLS).
- strup.org - WLSE by strup method.

- lme.sta - Stationary L-moment estimates.
- pen - Penalty method used.
- p\_q - (for beta) p and q values.
- c1\_c2 - (for beta) c1 and c2 values.

### Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

### References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. Journal of the Korean Statistical Society, 54, 947-970. doi:10.1007/s42952025003253

### See Also

[glme.gev](#) for stationary GEV estimation, [nsgev](#) for the pure L-moment wrapper (no penalty), [quagev.NS](#) for non-stationary quantile computation.

### Examples

```
# Load example streamflow data
data(streamflow)
x <- streamflow$r1

# Estimate non-stationary GEV11 parameters
result <- glme.gev11(x, ntry = 5)
print(result$para.glme) # Proposed GLME estimates
print(result$para.lme) # L-moment based estimates
```

---

glme.like

*Calculate the likelihood for Generalized L-moments estimation of GEV distribution*

---

### Description

This function calculates the likelihood (or more precisely, a penalized negative log-likelihood) for the Generalized L-moments estimation of the Generalized Extreme Value (GEV) distribution.

**Usage**

```
glme.like(
  par = par,
  xdat = xdat,
  slmgev = slmgev,
  covinv = covinv,
  lcovdet = lcovdet,
  mu = mu,
  std = std,
  lme = lme,
  pen = pen,
  p = p,
  c1 = c1,
  c2 = c2
)
```

**Arguments**

par	A vector of GEV parameters (location, scale, shape).
xdat	A numeric vector of data.
slmgev	Sample L-moments of the data.
covinv	Inverse of the covariance matrix of the sample L-moments.
lcovdet	Log determinant of the covariance matrix.
mu	Mean for the normal penalization (used when pen='norm').
std	Standard deviation for the normal penalization (used when pen='norm').
lme	L-moment estimates of the parameters.
pen	Penalization method: 'norm', 'beta', 'ms', 'park', 'cannon', 'cd', or 'no'.
p	Shape parameter for beta penalty.
c1	Scaling parameter for beta penalty.
c2	Upper limit parameter for beta penalty.

**Details**

The function performs the following steps: 1. Checks if the parameters are within valid ranges. 2. Calculates the expected L-moments based on the current parameters. 3. Computes the difference between expected and sample L-moments. 4. Calculates the generalized L-moments distance. 5. Applies a penalization term based on the specified method. 6. Returns the sum of the L-moments distance and the penalization term.

**Value**

A numeric value representing the penalized negative log-likelihood. A lower value indicates a better fit.

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

**See Also**

[glme.gev](#) which calls this function for optimization.

**Examples**

```
data(streamflow)
x <- streamflow$r1
slm <- lmomco::lmoms(x, nmom = 3)
cov_mat <- lmomco::lmoms.cov(x, nmom = 3)
lme_par <- lmomco::pargev(slm)$para
glme.like(par = lme_par, xdat = x, slmgev = slm,
          covinv = solve(cov_mat), lcovdet = log(det(cov_mat)),
          mu = -0.5, std = 0.2, lme = lme_par, pen = "beta",
          p = 6, c1 = 10, c2 = 5)
```

---

haenam

*Haenam Maximum Rainfall Data*

---

**Description**

Annual maximum daily rainfall data from Haenam, South Korea. This dataset is used for demonstrating model averaging methods for high quantile estimation in extreme value analysis.

**Usage**

haenam

**Format**

A data frame with 52 rows and 2 columns:

**year** Year of observation (integer, 1971-2022)

**X1** Annual maximum daily rainfall in mm (numeric)

**Source**

Korea Meteorological Administration (KMA; <https://www.weather.go.kr>)

## References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

## Examples

```
data(haenam)
head(haenam)

# Estimate high quantiles using model averaging
result <- ma.gev(haenam$X1, quant = c(0.98, 0.99, 0.995))
print(result$squa.ma)
```

---

init.glme	<i>Initialize random starting values for GLME optimization</i>
-----------	--

---

## Description

Generates multiple random starting parameter sets for multi-start optimization in GLME estimation. Uses L-moment estimates as a base and adds random perturbations.

## Usage

```
init.glme(xdat, ntry = ntry)
```

## Arguments

xdat	A numeric vector of data to be fitted.
ntry	Number of initial parameter sets to generate.

## Value

A matrix with ntry rows and 3 columns (location, scale, shape), where each row is a candidate starting point for optimization.

## Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

## See Also

[glme.gev](#) which uses this function internally.

**Examples**

```
data(streamflow)
inits <- init.glme(streamflow$r1, ntry = 5)
print(inits)
```

---

ma.gev

---

*Model Averaging for GEV High Quantile Estimation*


---

**Description**

This function estimates high quantiles of the Generalized Extreme Value (GEV) distribution using model averaging with mixed criteria. It combines Maximum Likelihood Estimation (MLE) and L-moment Estimation (LME) to construct candidate submodels and assign weights effectively.

**Usage**

```
ma.gev(
  data = NULL,
  quant = c(0.98, 0.99, 0.995),
  weight = "like1",
  numk = 12,
  B = 200,
  varcom = TRUE,
  trim = 0,
  fig = FALSE,
  bma = FALSE,
  pen = "norm",
  CD = FALSE,
  remle = FALSE
)
```

**Arguments**

data	A numeric vector of data to be fitted (e.g., annual maxima).
quant	The probabilities corresponding to high quantiles to be estimated. Default is c(0.98, 0.99, 0.995).
weight	The weighting method name. Options are: <ul style="list-style-type: none"> <li>• 'like', 'like0', 'like1' (default): Likelihood-based weights (AIC)</li> <li>• 'gLd', 'gLd0', 'gLd1', 'gLd2': Generalized L-moment distance weights</li> <li>• 'med', 'med1', 'med2': Median-based weights</li> <li>• 'cvt': Conventional AIC weights</li> </ul> Variants with numbers indicate left trimming level (0, 1, or 2).
numk	The number of candidate submodels K. Default is 12.
B	The number of bootstrap samples. Default is 200.

varcom	Logical. Whether to compute variance of quantile estimates. Default is TRUE.
trim	The number of left trimming for L-moments. Usually 0 (default), 1, or 2.
fig	Logical. Whether to produce diagnostic plots. Default is FALSE.
bma	Logical. Whether to use Bayesian Model Averaging. Default is FALSE.
pen	Penalty type for BMA prior: 'norm' (normal, default) or 'beta'.
CD	Logical. Whether to compute Coles-Dixon penalized MLE. Default is FALSE.
remle	Logical. Whether to compute restricted MLE. Default is FALSE.

### Details

The model averaging approach works as follows:

1. MLE and LME of GEV parameters are computed
2. K candidate shape parameters ( $\xi$ ) are selected from profile likelihood CI
3. For each candidate  $\xi$ , MLE with fixed  $\xi$  is computed
4. Weights are assigned based on the selected method
5. Final quantile estimates are weighted averages across submodels

The weighting schemes include:

- 'like': AIC-based weights using likelihood with fixed  $\xi$
- 'gLd': Weights based on generalized L-moment distance
- 'med': Weights based on median and L-moment distance
- 'cvt': Conventional AIC weights

When `bma=TRUE`, Bayesian model averaging is applied with prior specified by `pen`.

### Value

A list containing:

- `mle.hosking` - MLE estimates in Hosking style ( $\mu$ ,  $\sigma$ ,  $\xi$ )
- `qua.mle` - Quantile estimates from MLE
- `mle.cov3` - Covariance matrix of MLE (3x3)
- `qua.se.mle.delta` - Standard errors of MLE quantiles (delta method)
- `lme` - L-moment estimates ( $\mu$ ,  $\sigma$ ,  $\xi$ )
- `lme.cov3` - Covariance matrix of LME (bootstrap)
- `qua.lme` - Quantile estimates from LME
- `qua.se.lme.boots` - Standard errors of LME quantiles (bootstrap)
- `qua.ma` - Model-averaged quantile estimates
- `w.ma` - Weights used for model averaging
- `fixw.se.ma` - Asymptotic SE under fixed weights
- `ranw.se.ma` - Asymptotic SE under random weights

- `surr` - Surrogate model parameters ( $\mu$ ,  $\sigma$ ,  $\xi$ )
- `pick_xi` - Selected  $\xi$  values for K submodels
- `qua.bma` - (if `bma=TRUE`) BMA quantile estimates
- `w.bma` - (if `bma=TRUE`) BMA weights
- `mle.CD` - (if `CD=TRUE`) Coles-Dixon penalized MLE
- `qua.CD` - (if `CD=TRUE`) Quantile estimates from CD-MLE
- `remle1` - (if `remle=TRUE`) Restricted MLE (first constraint)
- `qua.remle1` - (if `remle=TRUE`) Quantile estimates from `remle1`
- `remle2` - (if `remle=TRUE`) Restricted MLE (second constraint)
- `qua.remle2` - (if `remle=TRUE`) Quantile estimates from `remle2`
- `quant` - The quantile probabilities used

### Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

### References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

### See Also

[glme.gev](#) for stationary GLME estimation, [magev.ksensplot](#) for K sensitivity analysis, [magev.qqplot](#) for Q-Q diagnostic plots, [magev.rlplot](#) for return level plots.

### Examples

```
# Load example data
data(streamflow)
x <- streamflow$r1

# Basic usage with likelihood weights
result <- ma.gev(x, quant = c(0.95, 0.99), weight = 'like1', B = 100)
print(result$qua.ma)      # Model-averaged quantiles
print(result$qua.mle)    # MLE quantiles for comparison
print(result$qua.lme)    # LME quantiles for comparison

# Using generalized L-moment distance weights
result2 <- ma.gev(x, quant = c(0.95, 0.99), weight = 'gLd', B = 100)
print(result2$w.ma)      # Model weights
```

---

magev.ksensplot      *K Sensitivity Plot for MAGEV*

---

### Description

Plots return level estimates, standard errors, and first-order differences across different numbers of candidate submodels  $K$ . This helps identify stable regions where estimates converge and select an optimal  $K$  value.

### Usage

```
magev.ksensplot(  
  data = NULL,  
  q.cut = 0.6,  
  mink = 4,  
  maxk = 20,  
  quant = c(0.99, 0.995)  
)
```

### Arguments

data	A numeric vector of data to be fitted (e.g., annual maxima).
q.cut	Quantile cutoff for determining stability (default 0.6).
mink	Minimum number of candidate submodels to test (default 4).
maxk	Maximum number of candidate submodels to test (default 20).
quant	The probabilities for high quantile estimation. Default is c(0.99, 0.995).

### Details

The function computes MAGEV estimates for  $K$  ranging from `mink` to `maxk`. For each  $K$ , it calculates:

- Return level estimates (black points)
- Normalized standard errors (blue line)
- First-order differences (red line with triangles)

The optimal  $K$  is selected as the smallest value where both the normalized standard error and first-order difference are below their respective `q.cut` quantile cutoffs. The selected  $K$  is indicated by a purple vertical line.

### Value

The optimal  $K$  value (integer) selected by the algorithm.

### Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

## References

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

## See Also

[ma.gev](#) for the main model averaging function.

## Examples

```
data(streamflow)
optimal_k <- magev.ksensplot(streamflow$r1)
print(optimal_k)
```

---

magev.qqplot

*Q-Q Diagnostic Plot for MAGEV*

---

## Description

Creates a 2x2 panel of Q-Q plots comparing observed vs. fitted quantiles for different estimation methods: MLE, LME, surrogate (MA), and REMLE.

## Usage

```
magev.qqplot(data = NULL, zx = NULL)
```

## Arguments

data	A numeric vector of observed data.
zx	A list object returned by <a href="#">ma.gev</a> with remle = TRUE.

## Details

The function creates four Q-Q plots:

- Upper left: MLE (Maximum Likelihood Estimation)
- Upper right: LME (L-moment Estimation)
- Lower left: Surrogate MA (Model Averaging surrogate)
- Lower right: REMLE (Restricted MLE, if available)

Points close to the 45-degree diagonal line indicate good model fit.

## Value

NULL. The function produces a plot as a side effect.

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

**See Also**

[ma.gev](#) for the main model averaging function, [magev.rlplot](#) for return level plots.

**Examples**

```
data(streamflow)
qq <- c(seq(0.01, 0.99, by = 0.01), 0.995, 0.999)
zx <- ma.gev(streamflow$r1, quant = qq, weight = 'like1',
             numk = 9, varcom = FALSE, remle = TRUE)
magev.qqplot(data = streamflow$r1, zx = zx)
```

---

magev.rlplot

*Return Level Plot for MAGEV*

---

**Description**

Displays fitted return levels with 95 return period on a log scale.

**Usage**

```
magev.rlplot(par = NULL, se.vec = NULL, data = NULL)
```

**Arguments**

par	A numeric vector of GEV parameters ( $\mu$ , $\sigma$ , $\xi$ ) in Hosking style. Typically from <code>zx\$surr\$par</code> where <code>zx</code> is the output of <a href="#">ma.gev</a> .
se.vec	A numeric vector of standard errors for the quantile estimates corresponding to the plotting positions. Typically from <code>zx\$ranw.se.ma</code> .
data	A numeric vector of observed data (annual maxima).

**Details**

The plot shows:

- Black line: Fitted return level curve
- Blue lines: 95
- Black points: Observed data at empirical return periods

The x-axis (return period) is on a log scale, ranging from 0.1 to 900 years.

**Value**

NULL. The function produces a plot as a side effect.

**Author(s)**

Yongwan Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y., & Park, J. S. (2026). Model averaging with mixed criteria for estimating high quantiles of extreme values: Application to heavy rainfall. *Stochastic Environmental Research and Risk Assessment*, 40(2), 47. doi:10.1007/s0047702503167x

**See Also**

[ma.gev](#) for the main model averaging function, [magev.qqplot](#) for Q-Q diagnostic plots.

**Examples**

```
data(streamflow)
ff <- c(seq(0.01, 0.09, by = 0.01), 0.1, 0.2, 0.3, 0.4, 0.5,
        0.6, 0.7, 0.8, 0.9, 0.93, 0.95, 0.98, 0.99,
        0.993, 0.995, 0.998, 0.999)
zx <- ma.gev(streamflow$r1, quant = ff, weight = 'like1',
            numk = 9, varcom = TRUE)
magev.rlplot(par = zx$surr$par, se.vec = zx$ranw.se.ma, data = streamflow$r1)
```

---

MS\_pk

*Martins-Stedinger prior function*

---

**Description**

Computes the Martins-Stedinger Beta(6,9) prior probability for the GEV shape parameter on the interval  $[-0.5, 0.5]$ .

**Usage**

```
MS_pk(para = para, p = 6, q = 9)
```

**Arguments**

para	A vector of GEV parameters (location, scale, shape).
p	Shape parameter for beta distribution (default 6).
q	Shape parameter for beta distribution (default 9).

**Value**

Prior probability value (scalar).

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Martins, E. S. & Stedinger, J. R. (2000). Generalized maximum-likelihood generalized extreme-value quantile estimators for hydrologic data. *Water Resources Research*, 36(3), 737-744. doi:10.1029/1999WR900330

**See Also**

[pk.beta.stnary](#) for the adaptive beta penalty, [glme.gev](#) which uses these penalty functions.

**Examples**

```
# Evaluate MS prior at xi = -0.2
MS_pk(para = c(100, 20, -0.2))
```

---

nsgev

*Non-stationary GEV Parameter Estimation*

---

**Description**

Estimates parameters of a non-stationary Generalized Extreme Value (GEV) distribution using the L-moment-based algorithm from Shin et al. (2025, *J. Korean Stat. Soc.*). This function combines L-moments, goodness-of-fit measures, and robust regression.

This is a convenience wrapper around [glme.gev11](#) with `pen="no"`, providing compatibility with the original nsgev package interface.

**Usage**

```
nsgev(xdat, ntry = 20, ftol = 1e-06)
```

**Arguments**

xdat	A numeric vector of data to be fitted (e.g., annual maximum values).
ntry	Number of attempts for optimization (default 20).
ftol	Function tolerance for optimization (default 1e-6).

**Value**

A list containing:

- `para.prop` - The proposed L-moment based estimates (`mu0`, `mu1`, `sigma0`, `sigma1`, `xi`).
- `precis` - Precision of the optimization.

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 54, 947-970. doi:10.1007/s42952025003253

**See Also**

[glme.gev11](#) for the full GLME method with penalty functions, [gado.prop\\_11](#) for detailed estimation results.

**Examples**

```
data(Trehafod)
result <- nsgev(Trehafod$r1, ntry = 5)
print(result$para.prop)
```

---

`pargev.kfix`

*GEV parameter estimation with fixed shape parameter*

---

**Description**

Estimates GEV location and scale parameters from L-moments while keeping the shape parameter fixed at a user-specified value. Modified from `lmomco::pargev()`.

**Usage**

```
pargev.kfix(lmom, kfix = 0.1, checklmom = TRUE, ...)
```

**Arguments**

<code>lmom</code>	L-moments object.
<code>kfix</code>	Fixed shape parameter value.
<code>checklmom</code>	Whether to check L-moment validity.
<code>...</code>	Additional arguments.

**Value**

A list with components:

**type** Character "gev"

**para** Numeric vector of GEV parameters (xi=location, alpha=scale, kappa=shape)

**source** Character "pargev"

**Author(s)**

Yongkwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Hosking, J. R. M. (1990). L-moments: Analysis and estimation of distributions using linear combinations of order statistics. *Journal of the Royal Statistical Society, Series B*, 52(1), 105-124. doi:10.1111/j.25176161.1990.tb01775.x

**See Also**

[glme.gev](#) for GLME estimation, [pargev](#) for the original L-moment GEV fitting.

**Examples**

```
data(streamflow)
lmom <- lmomco::lmoms(streamflow$r1, nmom = 3)
pargev.kfix(lmom, kfix = -0.1)
```

---

PhliuAgromet

*Phliu Agrometeorological Station Data*

---

**Description**

Climate or meteorological data from the Phliu Agrometeorological Station for extreme value analysis.

**Usage**

PhliuAgromet

**Format**

A data frame with 40 rows and 9 columns:

**Station.ID** Station identifier (character)  
**year** Year of observation (numeric, 1984-2023)  
**prec** Annual maximum daily precipitation in mm (numeric)  
**Name** Station name (character)  
**zone** Climate zone code (character)  
**latitude** Station latitude in degrees (numeric)  
**longitude** Station longitude in degrees (numeric)  
**Starting.year** Record start year (integer)  
**Ending.year** Record end year (numeric)

**Source**

Phliu Agrometeorological Station, Thailand.

**References**

Shin, Y., Shin, Y., Park, J., & Park, J. S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

**Examples**

```
data(PhliuAgromet)
head(PhliuAgromet)
```

---

pk.beta.stnary

*Beta preference function for stationary GEV*

---

**Description**

Computes a Beta distribution-based adaptive preference (penalty) function for the GEV shape parameter. The hyperparameters are adapted based on the L-moment estimate of the shape parameter.

**Usage**

```
pk.beta.stnary(
  para = NULL,
  lme.center = NULL,
  p = NULL,
  q = NULL,
  c0 = 0.3,
  c1 = 10,
  c2 = 5
)
```

**Arguments**

para	A vector of GEV parameters.
lme.center	L-moment estimates as center.
p	Shape parameter (default 6).
q	Shape parameter q (optional, if provided uses fixed limits).
c0	Limit parameter (default 0.3).
c1	Scaling parameter (default 10).
c2	Upper limit parameter (default 5).

**Value**

A list containing:

- pk.one** Preference function value (scalar)
- p** Shape parameter p used
- q** Shape parameter q used

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

**See Also**

[pk.norm.stnary](#) for the normal penalty, [MS\\_pk](#) for the Martins-Stedinger penalty, [glme.gev](#) which uses these penalty functions.

**Examples**

```
# Beta preference for xi = -0.2 centered at LME xi = -0.15
pk.beta.stnary(para = c(100, 20, -0.2),
               lme.center = c(100, 20, -0.15), p = 6)
```

---

pk.norm.stnary      *Normal preference function for shape parameter (stationary GEV)*

---

### Description

Computes a normal distribution-based preference (penalty) function value for the GEV shape parameter. The alias `new_pf_norm` is provided for backward compatibility.

### Usage

```
pk.norm.stnary(para = NULL, mu = NULL, std = NULL)
```

```
new_pf_norm(para = NULL, mu = NULL, std = NULL)
```

### Arguments

<code>para</code>	A vector of GEV parameters.
<code>mu</code>	Mean for normal distribution.
<code>std</code>	Standard deviation for normal distribution.

### Value

Preference function value (scalar).

### Author(s)

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

### References

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

### See Also

[pk.beta.stnary](#) for the beta penalty, [MS\\_pk](#) for the Martins-Stedinger penalty, [glme.gev](#) which uses these penalty functions.

### Examples

```
# Normal preference with mean=-0.5, sd=0.2 at xi=-0.2
pk.norm.stnary(para = c(100, 20, -0.2), mu = -0.5, std = 0.2)
```

---

`quagev.NS`*Quantile function for non-stationary GEV models*

---

**Description**

Calculates quantiles for non-stationary GEV models including GEV11, GEV10, GEV20, and stationary GEV00.

**Usage**

```
quagev.NS(f = NULL, para = NULL, nsample = NULL, model = NULL)
```

**Arguments**

<code>f</code>	Probability (or vector of probabilities) for quantile calculation.
<code>para</code>	Parameter vector. For GEV11: ( $\mu_0$ , $\mu_1$ , $\sigma_0$ , $\sigma_1$ , $\xi$ ).
<code>nsample</code>	Number of time points (sample size).
<code>model</code>	Model type: "gev11", "gev10", "gev20", "gev01", or "gev00"/"gev".

**Value**

A matrix of quantiles (`nsample` x `length(f)`) or a vector if `f` is scalar.

**Author(s)**

Yonggwon Shin, Seokkap Ko, Jihong Park, Yire Shin, Jeong-Soo Park

**References**

Shin, Y., Shin, Y., Park, J. & Park, J.-S. (2025). Generalized method of L-moment estimation for stationary and nonstationary extreme value models. arXiv preprint arXiv:2512.20385. doi:10.48550/arXiv.2512.20385

**See Also**

[glme.gev11](#) for non-stationary GEV estimation, [glme.gev](#) for stationary GEV estimation.

**Examples**

```
# GEV11 model: time-varying quantiles
para <- c(84.55, 1.03, 2.91, 0.009, -0.08) # mu0, mu1, sigma0, sigma1, xi
q99 <- quagev.NS(f = 0.99, para = para, nsample = 53, model = "gev11")
print(q99)
```

---

streamflow

*Streamflow Data*

---

### Description

Annual maximum streamflow measurements for extreme value analysis.

### Usage

streamflow

### Format

A data frame with 50 rows and 2 columns:

**Year** Year of observation (character)

**r1** Annual maximum streamflow value (numeric)

### Source

UK National River Flow Archive, Peak Flow Dataset (<https://nrfa.ceh.ac.uk/data/peak-flow-dataset>).

### References

Grego, J. M., Yates, P. A., & Mai, K. (2015). Standard error estimation for mixed flood distributions with historic maxima. *Environmetrics*, 26(3), 229-242. doi:10.1002/env.2333

Shin, Y., Shin, Y., & Park, J. S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 1-24. doi:10.1007/s42952025003253

### Examples

```
data(streamflow)
head(streamflow)
```

---

Trehafod

*Trehafod River Flow Data*

---

### Description

Annual maximum river flow data from the Trehafod gauging station in Wales, UK. This dataset is commonly used for demonstrating non-stationary extreme value analysis methods.

### Usage

Trehafod

**Format**

A data frame with 53 rows and 2 columns:

**Year** Year of observation (integer, 1968-2021)

**r1** Annual maximum river flow in cubic meters per second (m<sup>3</sup>/s)

**Source**

UK National River Flow Archive.

**References**

Shin, Y., Shin, Y. & Park, J.-S. (2025). Building nonstationary extreme value model using L-moments. *Journal of the Korean Statistical Society*, 54, 947-970. doi:[10.1007/s42952025003253](https://doi.org/10.1007/s42952025003253)

**Examples**

```
data(Trehafod)
head(Trehafod)
```

```
# Fit non-stationary GEV11 model
result <- glme.gev11(Trehafod$r1, ntry = 5)
print(result$para.glme)
```

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